Lafith Mattara

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Work Experience

R&D Engineer (AI/Robotics)

Feb 2024 - Now

Image-Guided Robotics, IIT Madras

Tamil Nadu. India

- Led a 3-member team in developing AI-driven computer vision modules for an autonomous antenatal ultrasound robotic system, serving as the principal developer and integrating deep learning for real-time fetal standard plane detection, segmentation, and biometry estimation.
- Adapted the **Segment Anything (SAM) foundation model** to be self-prompting for fetal ultrasound, achieving **96% specificity**, with an inference time of **12 ms per image**.
- Successfully deployed the model in a robotic prototype, reducing manual scanning time from 30-45 minutes to
 just 4 minutes, achieving an 85%+ efficiency improvement and enabling high-throughput prenatal screening.
- Showcased the system at the XVIII Clinical Ultrasonography in Practice (CUSP) conference, garnering significant interest from clinicians for its potential to enable large-scale automated prenatal screening.

Visiting Research Scientist

Jan 2023 - Dec 2023

Cancer Biology Lab, University of Alabama at Birmingham (UAB)

Alabama, USA

- Investigated the association between neighborhood deprivation, tumor microenvironment, and racial disparity in cancer outcomes. Presented findings as posters at ATTIS 2023 and O'Neal Comprehensive Cancer Center Research Retreat.
- Developed a multi-stage deep learning model for patch-level annotation of WSIs, achieving F1 score of 0.95 across 24 classes. A first-author manuscript based on this work is currently under preparation.

Project Engineer (AI/VR)

Nov. 2021 - Oct. 2022

Endoscopy Design and Development group, Healthcare Technology Innovation Centre, IIT Madras Tamil Nadu, India

- Designed and developed a VR application for stereo-endoscope visualization from start to completion, integrating video capture, image processing, and 3D rendering. Delivered a fully functional system before transitioning from the company.
- Enabled the team to showcase the Stereo Endoscope VR system at MEDICA 2024 after competitive selection, demonstrating its impact on medical imaging and real-time visualization.
- Implemented deep learning models for polyp detection and deployed them on edge devices, optimized for real-time performance.

Project Intern

May 2021 – July 2021

Center for Computational Imaging, IIT Palakkad

Kerala, India

• Implemented **contrast enhancement** algorithms for **industrial CT** images in collaboration with VisiConsult, Germany.

EDUCATION

National Institute of Technology Rourkela (NITRKL)

Odisha, India

Bachelor of Technology in Biomedical Engineering (First Class)

Aug. 2017 - July 2021

- Led Simulator development team for Autonomous Underwater Vehicle development group.
- Contributed to creative content writing as a short story writer for the college magazine.

TECHNICAL SKILLS

Artificial Intelligence & Machine Learning (AI/ML): Deep Learning, CNN, GNN, Transformers, Generative models, Large Language Models (LLM), Foundation models, Distributed training.

Languages: Python, C/C++, C#, R Frameworks: PyTorch, Tensorflow, ROS

Libraries: Sklearn, OpenCV, Scipy, PIL, SkImage, Kornia, Pandas, NumPy, Matplotlib

Additional Tools: Unreal Engine 5, Unity

PROJECTS

AUV Simulator: Developed a **3D underwater vehicle simulator** using **Unity and ROS**, leading to a first-place win at the **SAVe 2019** competition, conducted by National Institute of Ocean Technology (NIOT), IEEE-OES, Marine Technology Society (MTS), and Ocean Society of India (OSI).